CM10 motor LN2 test report

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Introduction



VSS32 Motor with elongated shaft

Configuration reminder :

- Production tuner with CM10 motor
 - Had firstly completely failed, only at low temperature, during the LHe qualification of cryomodule CM10 at Uppsala
 - Similar to CM3 test (replacement, and reparation of the motor)
 - Works always well at room temperature (but not tested at full torque)
 - Had previously failed twice in a row, even after rising the current from 0.6 to 1.0 A
 - Equipped with its copper collar
 - Equipped with elongated shaft
- Production tuner with prototype motor
 - Never failed in any configuration/project thus never extensively tested
 - Assembling variations already known : bearing adjustment, bearing coating

Goal: Observe any variation by adding elongated shaft that could confirm gearbox shaft misalignment theory proposed during previous meeting.

- 1. Very first attempts failed
- 2. Then it started to move properly
- 3. And then quickly started to get stuck more and more
- 4. Finally stuck again



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- Large stroke testing (1.0 A), round trip
- ➔No issue
- ➔ Hysteresis on CM10 motor tuner mostly imputed to mechanical slight issue, sometimes observed on some tuner testing. Not motor related.



- Single way to 5,120 rev (1.0 A)
- →No issue, good correlation with round trip of the day before



Day 2 round trip

Day 3 single way

- Evaluation of motor start current from 1.0 A down to 0.32 A → OK (!!)
- Stress test 10,000 motor rev. (input of gearbox, not output), at <u>0.4 A</u> → OK (!!)



Again, stress test 10,000 motor rev. (input of gearbox, not output), at 0.4 A → OK



- Again, stress test 10,000 motor rev. (input of gearbox, not output), at 0.4 A → NOK (1)
- Put tuner at 2,560 rev (1.0 A) → OK
- Evaluation of motor start current from 1.0 A down to 0.32 A → OK (!!)
- Again, stress test 10,000 motor rev. (input of gearbox, not output), at 0.4 A → NOK (2)



Overview

- Day 1 Monday
 - Stuck at the very beginning, then work for a while until lost of steps
 - Loss of steps, more and more at half-nominal current (0.6 A)
 - Motor works if the current is pushed to 1.0 A (driver limit)
- Day 2 Tuesday
 - Large tuner stroke measurement at 1.0 A ($0 \rightarrow 5,120 \text{ rev}$) $\rightarrow \text{Passed}$ (max stroke : 5,888 rev)
- Day 3 Wednesday
 - Put tuner at 5,120 rev position using 1.0 A → Passed
 - Start current motor measurement : 0.32 A
 - Stress test at 0.4 A : 10,000 rev around the max position → Passed
- Day 4 Thursday
 - Stress test again → Passed
- Day 5 Friday
 - Stress test again → Failed
 - Recovery by pushing the current again to 1.0 A → Ok
 - Moving to lower position (2,560 rev) at 1.0 A → Ok
 - Start current motor measurement : 0.32 A
 - Stress test again at 0.4 A → Failed after few successful cycles
- Day 6 Monday
 - Quick trials, motor seems ok to work only if current is pushed (0.8 A / 1.0 A tested)

Conclusions

- Elongated shaft seems to have improved the motor behavior (previous attempts of current rising always failed at LT)
- Still, this system is not sufficient to fully recover the motor presumably damaged since cryomodule qualification
- Performances have been temporarily restored even at very low current (0.32 A around max position)

Next steps :

- Test without copper collar to identify any performance variation (W.49)
- Stress test with fresh motors w/ and w/o elongated shaft (W.50/51)

Further more :

- Test of old CM3 failed motor (which was repaired by Phytron early this year)
- Test of 2nd batch motor (2019 procurement vs 2017, clearly not the same play on output shaft)
- Internal inspection, coating wear evaluation, dimensional measurement around front bearings)

Full explanation tentative of the root cause (to be consolidated) :

Motor issue observed on LHe cryomodules qualification (at least CM10 and CM3, after having solved the driver current issue) might be explained by the addition of <u>2 causes</u>:

- 1. Misalignment of shaft : Allows high contact mechanical stress of internal pinions of planetary gearbox due to mechanical interference of the teeth.
- 2. Weak pinions coating : ADLC (amorphous carbon) appears to have a limited lifetime in vacuum, which can be strongly reduced depending of mechanical contact pressure. This also seems antagonist with MoS2 / Ws2 coating where friction rate (and then wear rate) drops when high contact pressure are applied

Both causes participated to quick degradation of the coating while maintaining a steel on steel high pressure contact leading to galling issue (friction coefficient super high). At room temperature (but possibly especially at 1 bar), the steel on steel interface is less an issue.