# Measurement of phase space density evolution in MICE Step IV

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#### Experimental apparatus at present (Step IV)



#### All the detectors are installed and working

- Three time-of-flight (TOF) detector stations
- Two Cherenkov counters and a downstream calorimetry module
- Two scintillating-fibre trackers
- Part of the cooling channel (no RF yet)
  - Two Spectrometer Solenoids (SS): 5 coils each
    - > The two downstream match coils are currently not turned on
  - An Absorber Focus Coil (AFC): 2 coils + absorber



#### Beam cooling setting optimization



Suitable optics have been found using two approaches to conjointly optimize transmission and cooling performance:

- Linear optics, scan in the parameter space of magnet currents;
- Genetic algorithm, best sets of optics bear the next generation, penalize transmission loss and encourage emittance reduction.

The **bottom lattice** setting is expected to have one of the best cooling performance – transmission trade-off and is **presented in the following** 



## Reproduction of optical functions in the simulation



z [mm]

Reliable reproduction of the data in the simulation for

- $\circ~\sim$  6 mm input beam
- $\circ$  140 MeV/c central momentum
- $\circ$  -0.68 central  $lpha_{\perp}$
- 787 mm central  $\beta_{\perp}$
- $\rightarrow$  Excellent tool to systematically test novel density methods



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#### Particle selection

Series of cuts applied to both data and simulation:

- Muon tagging using TOF01 (Particle ID)
- Upstream reference plane hit (Reference)
- Good track reconstruction quality (Quality)
- Track within the tracker fiducial (Aperture)
- Longit. momentum  $\in [135, 145] \text{ MeV}/c$  (Momentum)



#### Transverse normalised RMS emittance



4D normalised RMS emittance:

$$\epsilon_n = \frac{1}{m} |\Sigma|^{\frac{1}{4}} \,, \tag{1}$$

with  $|\boldsymbol{\Sigma}|$  the determinant of the covariance matrix defined as

$$\Sigma = \begin{pmatrix} \sigma_{xx} & \sigma_{xp_x} & \sigma_{xy} & \sigma_{xp_y} \\ \sigma_{p_xx} & \sigma_{p_xp_x} & \sigma_{p_xy} & \sigma_{p_xp_y} \\ \sigma_{yx} & \sigma_{yp_x} & \sigma_{yy} & \sigma_{ypy} \\ \sigma_{p_yx} & \sigma_{p_yp_x} & \sigma_{p_yy} & \sigma_{p_yp_y} \end{pmatrix}.$$
 (2)



The RMS emittance is directly related to the volume of the RMS ellipsoid through  $\epsilon_n = \sqrt{2V_{\text{RMS}}}/(m\pi)$  and as such is the most common probe of average phase space density:

$$\rho_{\rm RMS} = \frac{N}{V_{\rm RMS}} = \frac{N}{\frac{1}{2}m^2\pi^2\epsilon_n^2} = \frac{N}{\frac{1}{2}\pi^2|\Sigma|^{\frac{1}{2}}} \quad [{\rm mm}^{-2}({\rm MeV}/c)^{-2}].$$
(3)

 $\rightarrow$  It follows from Liouville's theorem that the phase space volume should be conserved

#### Emittance evolution





#### Power of density estimation



The emittance plot exhibits two obvious challenges:

- transmission losses yield apparent emittance reduction;
- filamentation in SSD yield apparent emittance growth.
- The key to solving both problems lies in density estimation:
  - Estimate density in the transverse 4D phase space (center figure);
  - Select an **identical fraction** of the beam upstream and downstream from within the **densest area of the space** (*right figure*);
  - Define cooling figure of merits on these subsamples;
  - $\rightarrow$  The core, unlike the tails, is **<u>transmitted</u>** and <u>linear</u>.



#### Transverse single-particle amplitude

Single particle amplitude is defined as

$$A_{\perp} = \epsilon_n \mathbf{u}^T \Sigma^{-1} \mathbf{u} \tag{4}$$

with  $\mathbf{u} = \mathbf{v} - \boldsymbol{\mu}$ , the centered phase space vector,  $\mathbf{v} = (x, p_x, y, p_y)$ , of the particle.

- It is related to the volume of an ellipse, which is similar to the RMS ellipse, going through v.
- Amplitude follows a  $\chi^2$  distribution with d degrees of freedom



$$\rho(\boldsymbol{v}_i) = \frac{1}{(2\pi)^2 |\Sigma|^{\frac{1}{2}}} \exp\left[-\mathbf{u}^T \Sigma^{-1} \mathbf{u}/2\right] = \left[\frac{1}{4\pi^2 m^2 \epsilon_n^2} \exp\left[-\frac{A_\perp}{2\epsilon_n}\right]\right].$$
 (5)

 $\rightarrow$  Allows for the selection of a high density core





#### Amplitude reconstruction



In the case of non-linear beams, special care must be taken in the reconstruction of amplitude as tails significantly bias the covariance matrix

Optimal procedure for amplitude reconstruction:

- $\circ~$  Compute  $\Sigma~$  and  $\mu~$  for the whole sample;
- 1 Calculate all the particle amplitudes  $A^i_{\perp}$ ;
- 2 Register the highest amplitude in the distribution;
- 3 Update  $\Sigma$  and  $\mu$  by removing the highest amplitude point;
- 4 Iterate from 1.



Amplitudes at TKD station 5







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#### Amplitude distribution evolution



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#### Subemittance definition and properties



The  $\alpha$ -subemittance,  $e_{\alpha}$ , is defined as the emittance of the core fraction  $\alpha$  of the parent beam. For a truncated 4D Gaussian beam of covariance matrix S, it satisfies



The statistical uncertainty carried by this measurement is identical to that of the emittance, scaled by the fraction  $\alpha$  as

$$\frac{\sigma_{e_{\alpha}}}{e_{\alpha}} = \frac{1}{\sqrt{\alpha}} \frac{\sigma_{\epsilon_n}}{\epsilon_n} = \sqrt{\frac{2}{\alpha N d}}.$$
(8)

#### Subemittance evolution





#### Fractional emittance definition and properties



The  $\alpha$ -fractional emittance,  $\epsilon_{\alpha}$ , is defined as the phase space volume occupied by the core fraction  $\alpha$  of the parent beam. For a truncated 4D Gaussian beam of covariance matrix S, it satisfies



In 4D, a fraction  $\alpha$  of  $\mathbf{9\%}$  yields the volume of the RMS ellipsoid,  $V_{\rm RMS}$ 

The **convex hull** is a prime candidate for volume reconstruction. It computes the smallest volume that contains the core  $\alpha N$  points.



#### Phase space volume evolution





## Toy analysis of fractional quantities



A toy analysis (Gaussian input beam, toy absorber) shows:

- The **same relative change** is seen in the RMS emittance and all of the fractional quantities, for any fraction
- The change in fractional quantities exhibit the same relation with  $\beta_{\perp}$  and the input emittance,  $\epsilon_i$
- The fractional quantities are **more robust** against losses and non-linearities as the tails do not influence their measurement



 $\rightarrow$  Plots produced for a core 9 % selection, i.e. size of the RMS ellipse

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#### Non-parametric density estimation: kNN

For a given point x, find the k closest points in the input cloud. Find the distance  $R_k$  to the  $k^{th}$  point and compute the 4D local density estimate as

$$\rho(\boldsymbol{x}) = \frac{k}{\mathcal{V}_k} = \frac{2k}{\pi^2 R_k^4},$$
 (11)

with  $\mathcal{V}_k$  the volume of the 4-ball centred in  $\boldsymbol{x}$  of radius  $R_k$ .

- Rule of thumb choice of  $k = \sqrt{N}$  yields quasi-optimal results for a broad array of distributions.
- Right plot shows great agreement between Cauchy distribution (red) and estimation (blue).









#### Density estimation at TKD station 5



#### Phase space volume evolution





#### Conclusions



Status of the amplitude-based analysis:

- Selecting the low amplitude core gets rid of apparent emittance reduction due to scraping and apparent emittance growth due to beam filamentation in the downstream section;
- A toy MC shows that the **exact same behaviour** is observed for the subemittance and fractional emittance as for the RMS definition;
- Method shows a **clean cooling signal** in a realistic MC.

Status of the non-parametric analysis:

- Systematic study well advanced, *k***NN robust in 4D**, low error and bias for large samples with the rule-of-thumb *k* selection;
- Method applied to the toy MC to study its behaviour, identical trend as with the amplitude-based fractional emittance;
- Method also shows **cooling signal** in a realistic MC.

# Back-up slides

#### Convex hull volume uncertainty

Computing the volume of the convex hull of a core fraction  $\alpha$  of a set of N i.i.d. random  $d\text{-}\mathsf{Gaussian}$  points yields

$$\frac{E[\hat{V}-V]}{V} \sim -(1+C^{-\frac{d+1}{2}}\alpha N)^{\frac{-2}{d+1}}, \qquad \left|\frac{\sigma_{\hat{V}}}{\hat{V}} \sim \sqrt{\frac{1-\alpha}{\alpha N}}\exp\left[Q_{\chi_d^2}(\alpha)/4\right]\right|$$
(12)

The factor C is purely deterministic, albeit complex in nature...

$$C = \frac{d+1}{2(d+3)(d-1)!} \Gamma\left(\frac{d+3}{d+1} + d\right) \left(\frac{2\pi}{B\left(\frac{1}{2}, \frac{d}{2} + 1\right)}\right)^{\frac{2}{d+1}}$$
(13)



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#### Density estimator Mean Integrated Squared Error



A critical characteristic of estimators is **consistency**. For large N, the estimator must converge to the true value that is estimated,

$$\lim_{N \to +\infty} \hat{\theta}_N = \theta.$$
 (14)

Deviation from the true estimated distribution can be quantified by computing the Mean Integrated Squared Error (**MISE**).



#### Contour volume reconstruction

In 4D, the most efficient way to estimate an arbitrary volume is to generate **random points** inside a 4-box that bounds the contour and to count the amount of points that are above the contour level.

This is a Binomial process which yields an uncertainty of

$$\frac{\sigma_{\hat{V}}}{\hat{V}} = \sqrt{\frac{1-\xi}{\xi N}}, \qquad \xi = \frac{N_{\text{in}}}{N}.$$
(15)





#### kNN contour volume bias and uncertainty

In addition to the counting error, which **can be tamed** by adding random points, there is a certain level of uncertainty related to the density estimation. The bias and variance satisfy

$$\frac{E[\hat{V}-V]}{V} \propto (\alpha N)^{-1/\lambda}, \qquad \qquad \frac{\sigma_{\hat{V}}}{\hat{V}} \sim \sqrt{\frac{1-\alpha}{\alpha N} \frac{\rho_0}{\rho_\alpha}}, \qquad (16)$$

which are distribution dependent.





