

Accelerators and Magnets 2

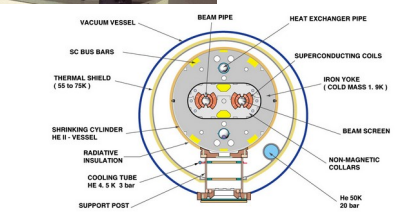
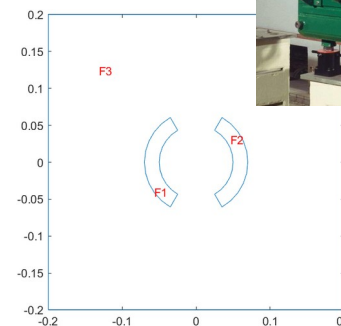
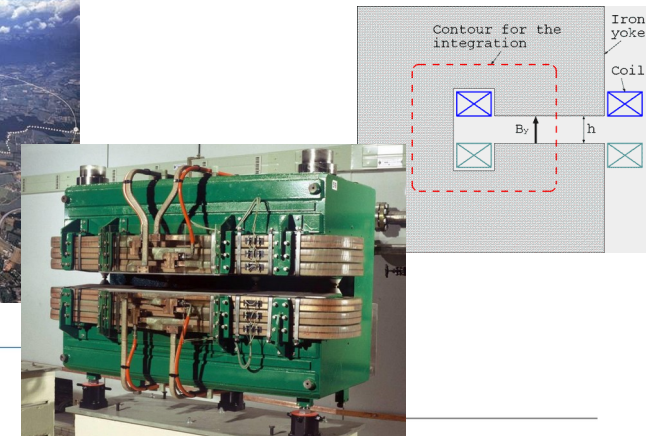
Volker Ziemann, FREIA

Last time:

- * Accelerators: LHC, MAX IV, ...
- * Iron dominated magnets
- * Superconducting magnets

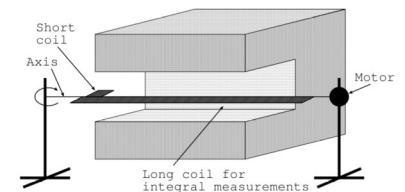
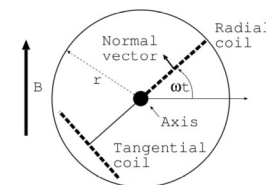
This time:

- * Permanent magnets
- * Magnetic measurements
- * Alignment

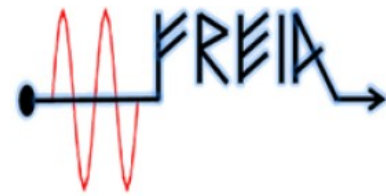


Today's roadmap

- Remember the multipoles
- Permanent magnet
 - material
 - multipole magnets
 - undulators
 - solenoids
- Magnetic measurements
- Alignment of magnets

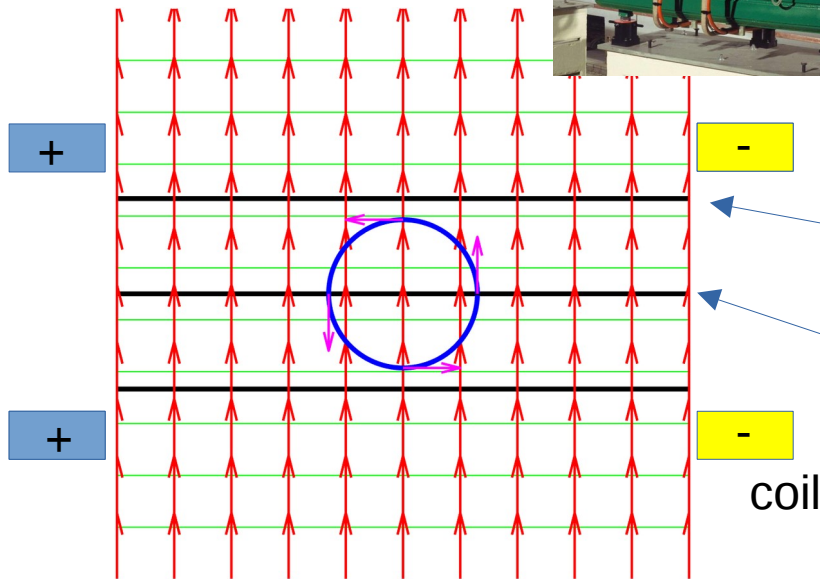
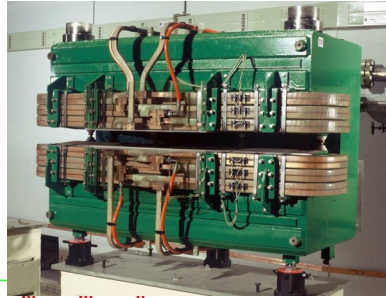


Multipole fields



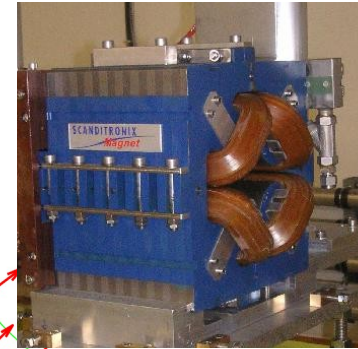
Dipole

$m=1$



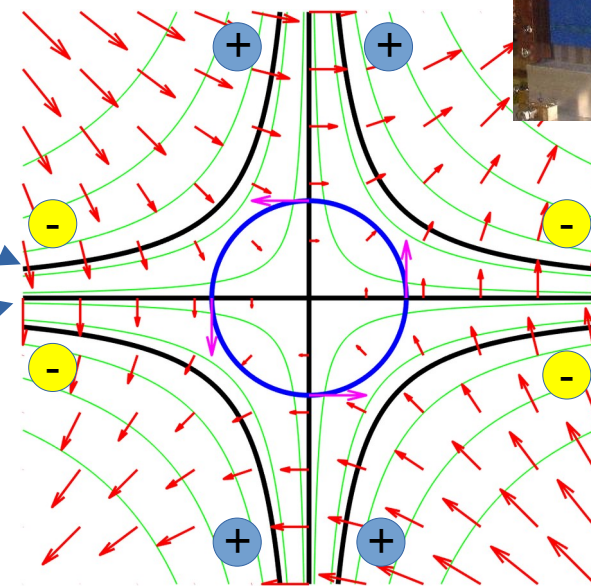
Quadrupole

$m=2$



pole face

midplane

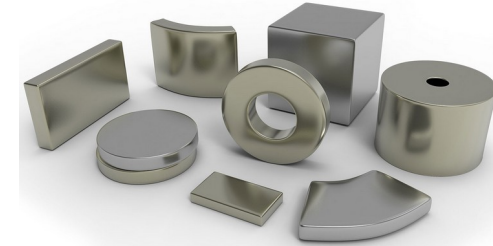


$$B_y + iB_x = B_0 \left(\frac{x + iy}{R_0} \right)^{m-1} = B_0 \left(\frac{r}{R_0} \right)^{m-1} e^{i(m-1)\phi}$$

m : magnitude $\sim r^{m-1}$, angle $\sim (m-1)\phi$

Permanent magnet material

- Magnets with large remanent field B_r
 - SmCo ($B_r \sim 1\text{T}$), NdFe ($B_r \sim 1.4\text{T}$)



from: www.arnoldmagnetics.com

- Transparent to external magnetic fields
 - relative permeability $\mu_r \sim 1$

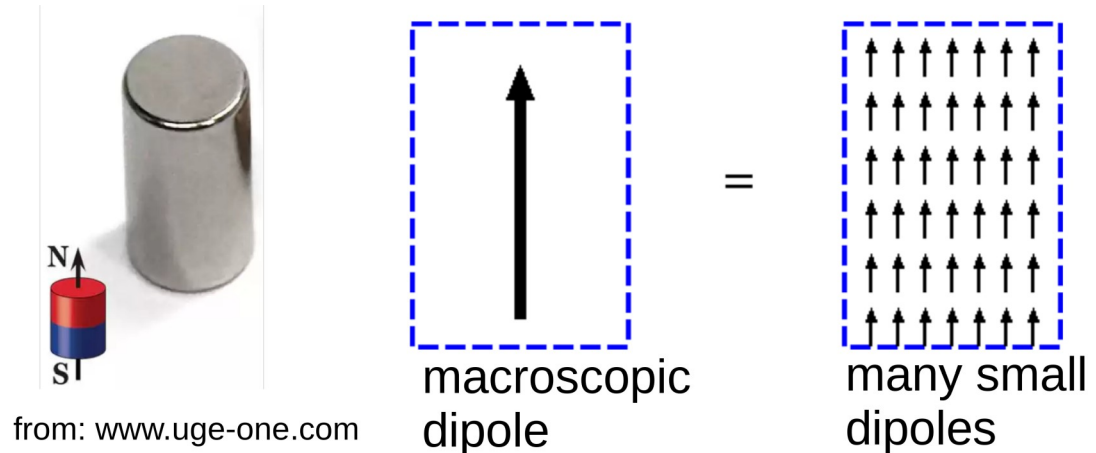
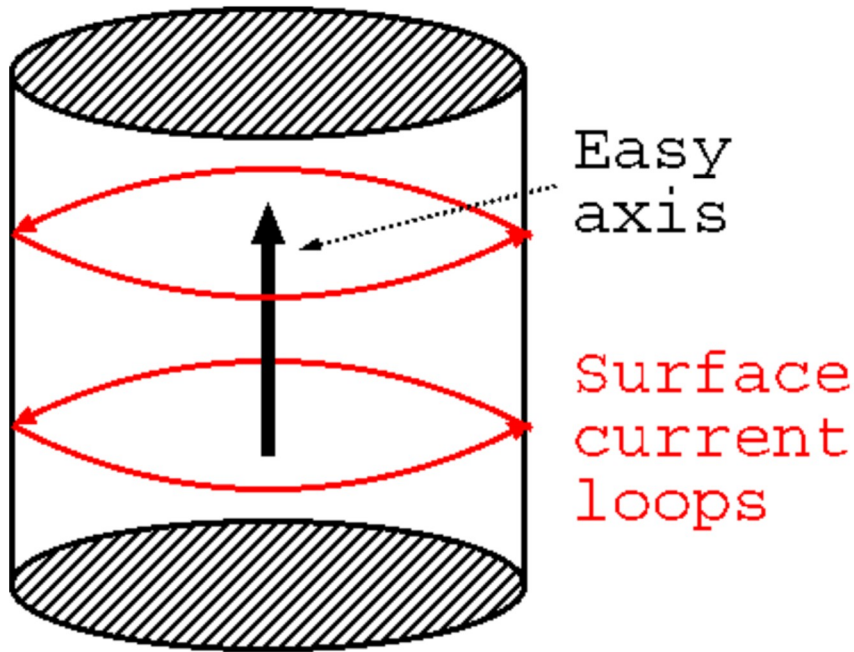
- Manufacture

- Heat powder mixture to melt and rapidly cool
- Grind to make powder, expose to strong field \rightarrow aligns spins
- *Sintering*: heat and compress
- Expose to even stronger field (imprints field \rightarrow easy axis)





How do they behave?

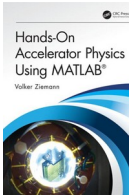
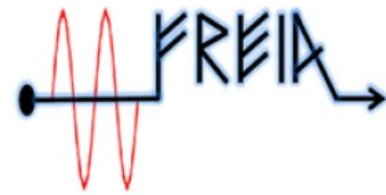


Calculate field of several PM as the **superposition** of the individual fields.

Like

- * a **flux-pump** for field lines
- * a **coil** around the surface carrying a very large current
- * many many **small dipoles**, all aligned
- * empty space (**transparent** to external magnetic fields)

PM dipoles

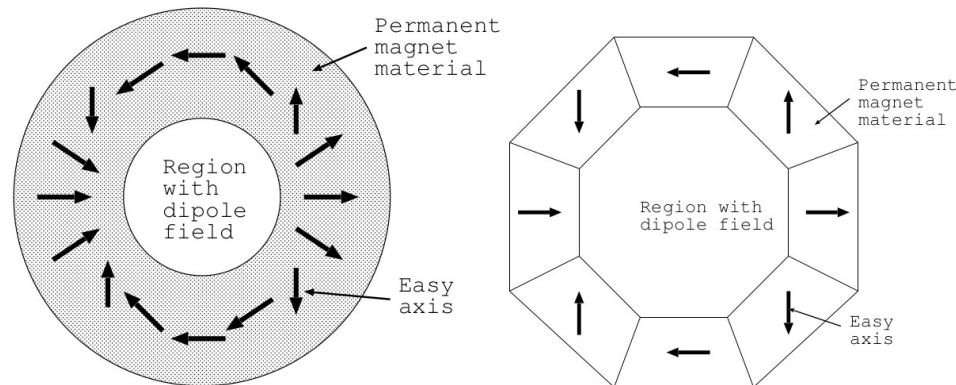
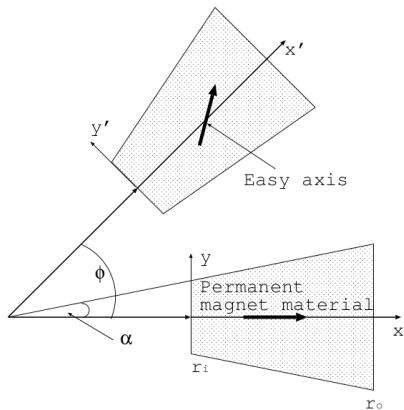


How much multipole does each small cube contribute?

- integrate/sum over all small dipoles

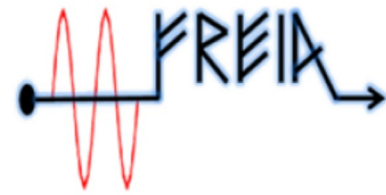
$$\underline{B}^*(\hat{z}) = \sum_{m=0}^{\infty} \left[\frac{m+1}{2\pi} \int_{\Omega} \frac{\underline{B}_r}{z^{m+2}} dx dy \right] \hat{z}^m$$

Cubes are easier to find than wedges - little more algebra with the integrals

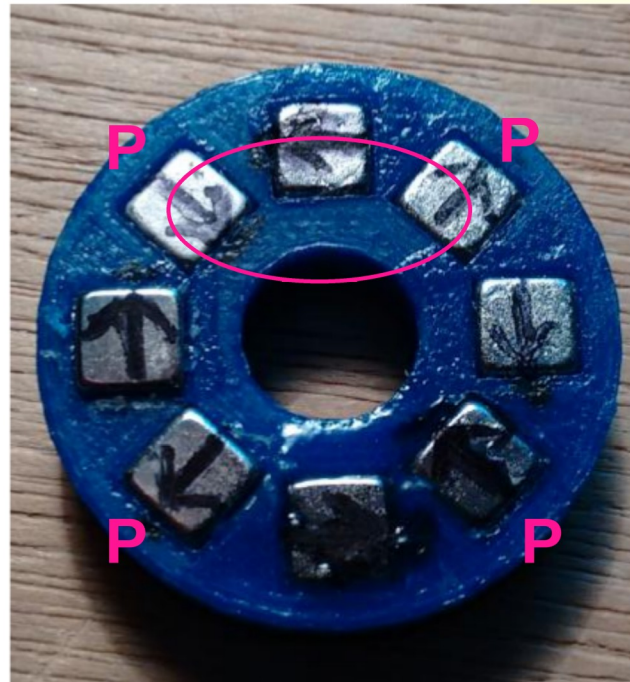
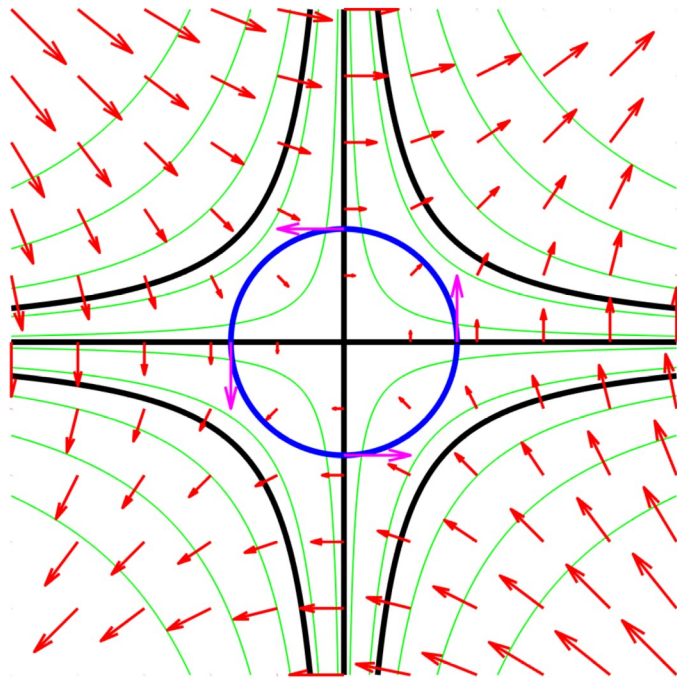
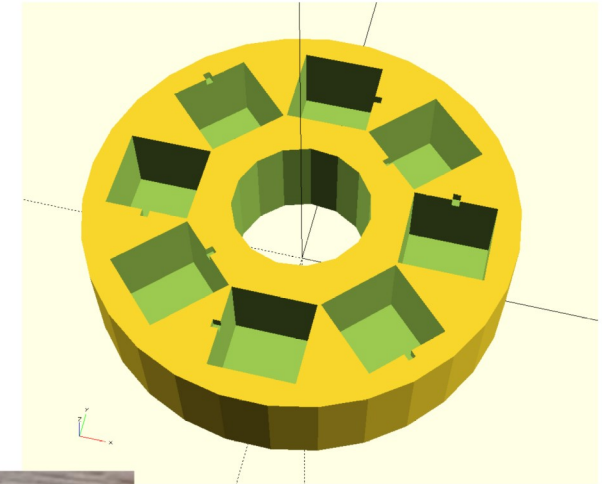




PM quadrupoles

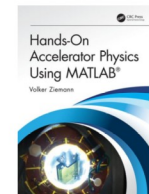


Mark cubes and place
with tumble factor $m=2$
in 3D printed frame



PM cubes pump
flux lines around
loops that create
the field for the
beam in the center.

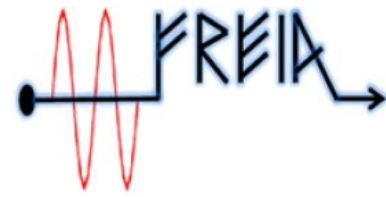
Also analytically
calculated fields!



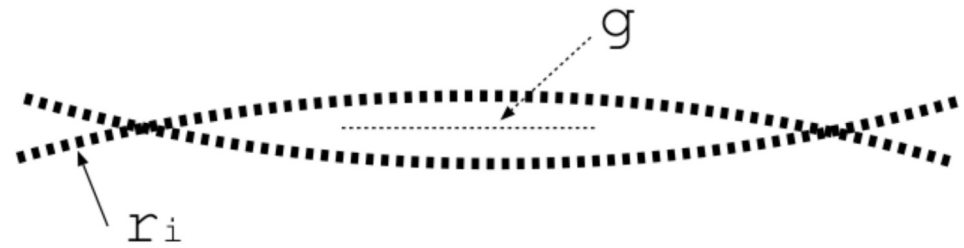
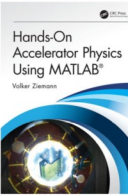
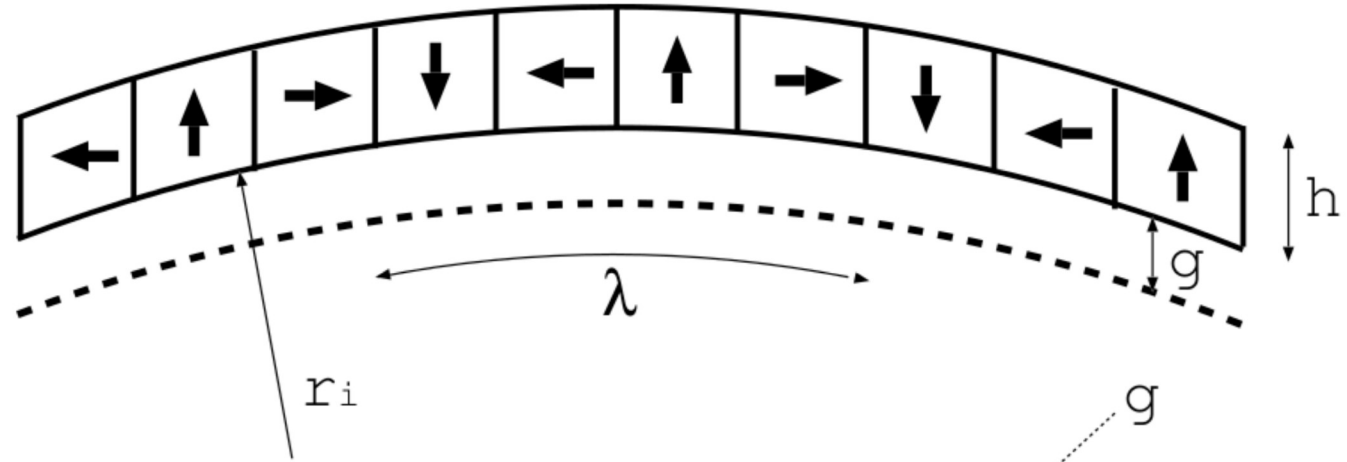


PM undulators

Speciality magnets to produce synchrotron radiation



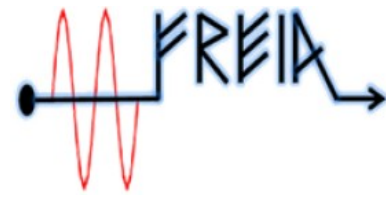
Make assembly larger and larger, while maintaining the size of the cubes



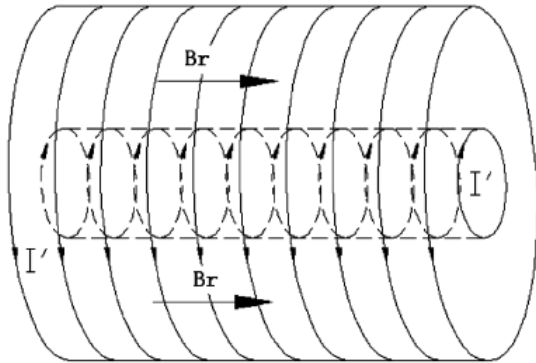
Derive magnetic field in gap entirely analytically from first principles

$$\hat{B}^*(\hat{z}) = iB_r \frac{\sin(\pi/4)}{\pi/4} (1 - e^{-2\pi h/\lambda}) e^{-2\pi g/\lambda} \cos(2\pi z/\lambda)$$

PM solenoids

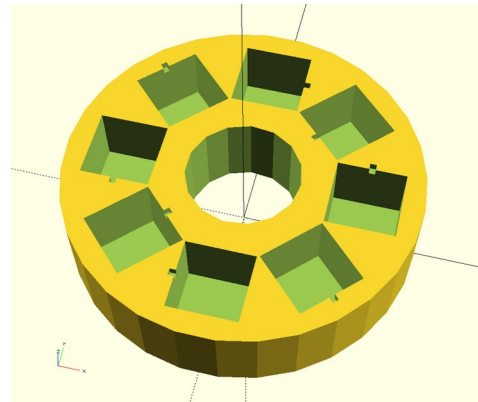
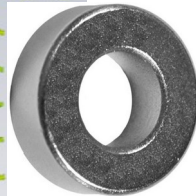
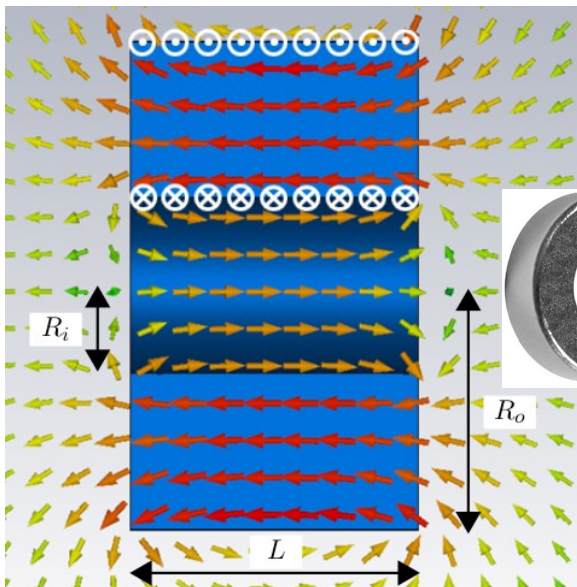


Axial magnets

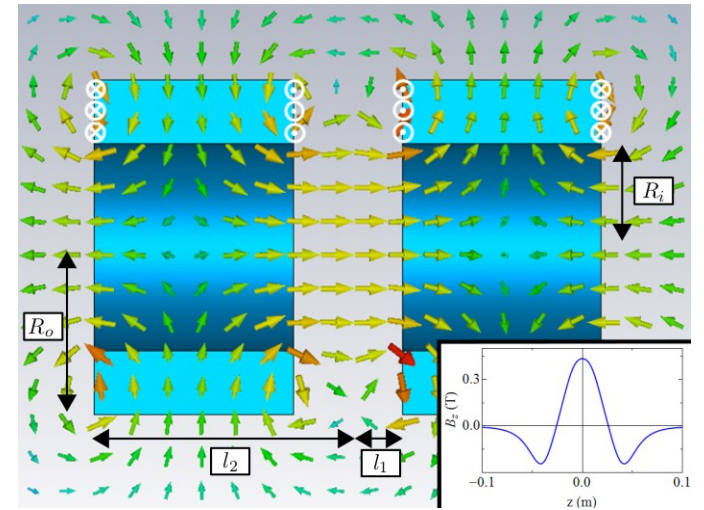


On-axis field can be calculated analytically (inner coil+outer coil)

$$B(z) = \frac{B_r}{2} \left[\left(\frac{z+l}{\sqrt{(z+l)^2 + R_2^2}} - \frac{z-l}{\sqrt{(z-l)^2 + R_2^2}} \right) - \left(\frac{z+l}{\sqrt{(z+l)^2 + R_1^2}} - \frac{z-l}{\sqrt{(z-l)^2 + R_1^2}} \right) \right]$$



Radial magnets



Radial magnets
- Easy axis points 'inwards'

Axial magnets
- Easy axis points 'forwards'



Magnetic measurements with a Hall sensor

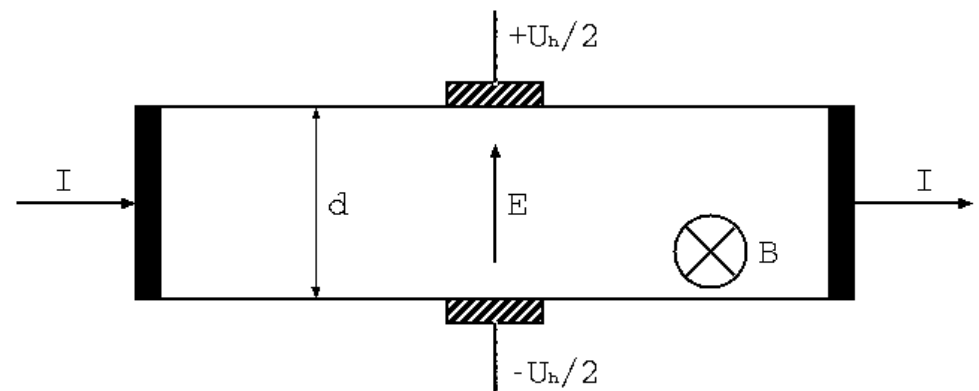
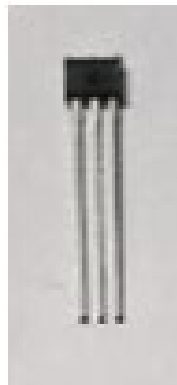
- Magnetic field measurements
 - Pass current I through semi-conductor (left-to-right)
 - Perpendicular magnetic field B deflects charge carriers to upper and lower contacts
 - Charges accumulate and create electric field E to balance the magnetic deflection

– $U_h = Ed$

– A1324

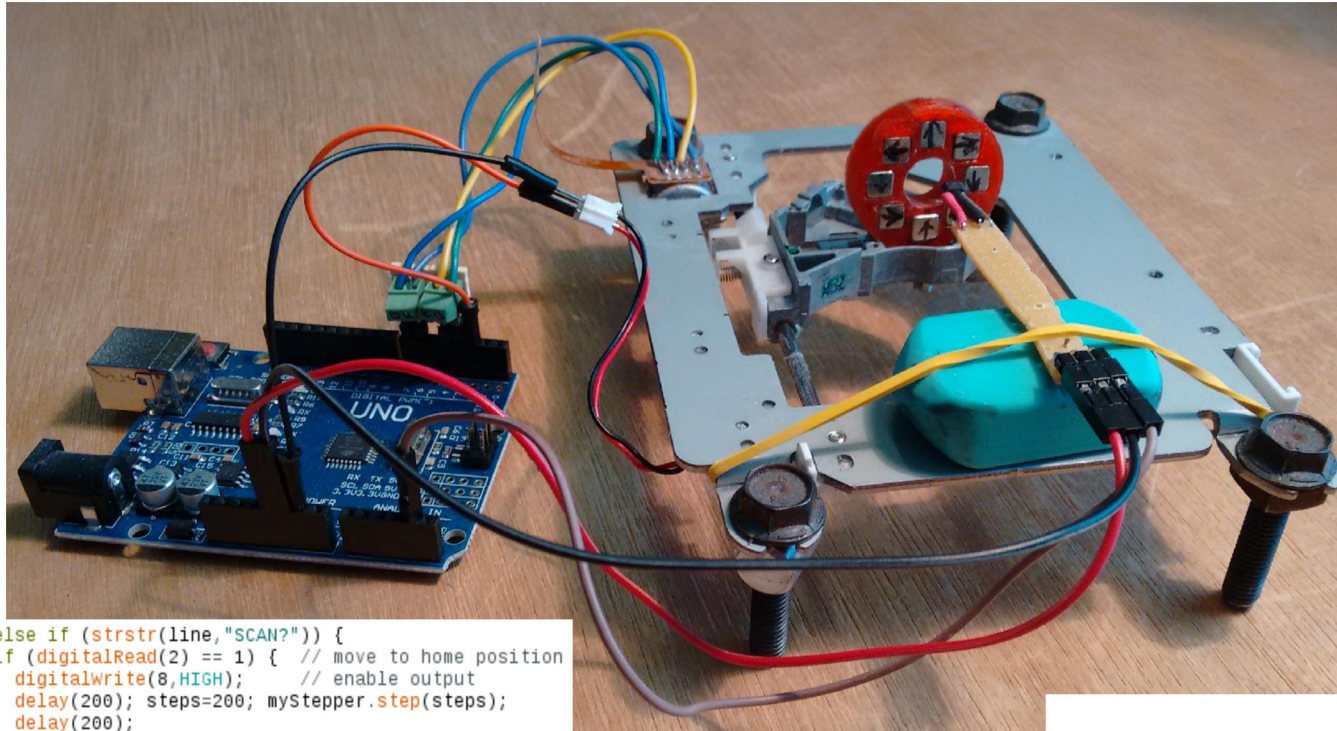
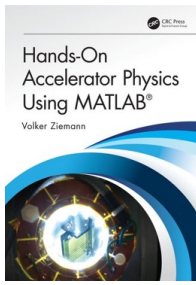
- V_c, GND, U_h

- 50 mV/mT





Measurement rig (conceptual)



Frame from an old CD drive with stepper motor driven by an Arduino.

Control via RS-232 (USB) from MATLAB

Software available from <https://www.crcpress.com/9781138589940>

```

} else if (strstr(line,"SCAN?")) {
  if (digitalRead(2) == 1) { // move to home position
    digitalWrite(8,HIGH); // enable output
    delay(200); steps=200; myStepper.step(steps);
    delay(200);
  }
  Serial.println("SCAN");
  digitalWrite(3,HIGH);
  for (int i=0;i<150;i++) {
    steps=-1; myStepper.step(steps);
    delay(100);
    float B=1e-4*(5.0*analogRead(1)/1023-2.4)/1.3e-3;
    Serial.println(B,4);
  }
  digitalWrite(3,LOW);
}

```

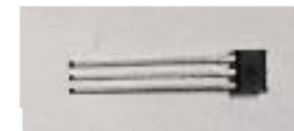
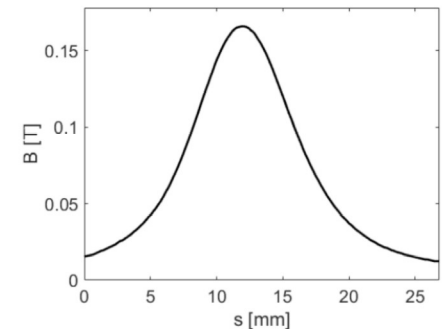
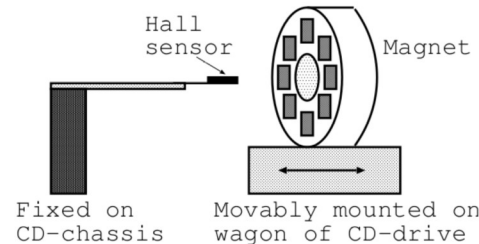
Arduino

```

fprintf(s,'SCAN?'); fscanf(s); % read the "SCAN" echoed
Bfield=zeros(1,150);
for i=1:150 % loop over the data points
  Bfield(i)=str2double(fscanf(s)); % string to double
end
xscale=0.18*(0:149); % 0.18 mm/motor step
plot(xscale,Bfield)

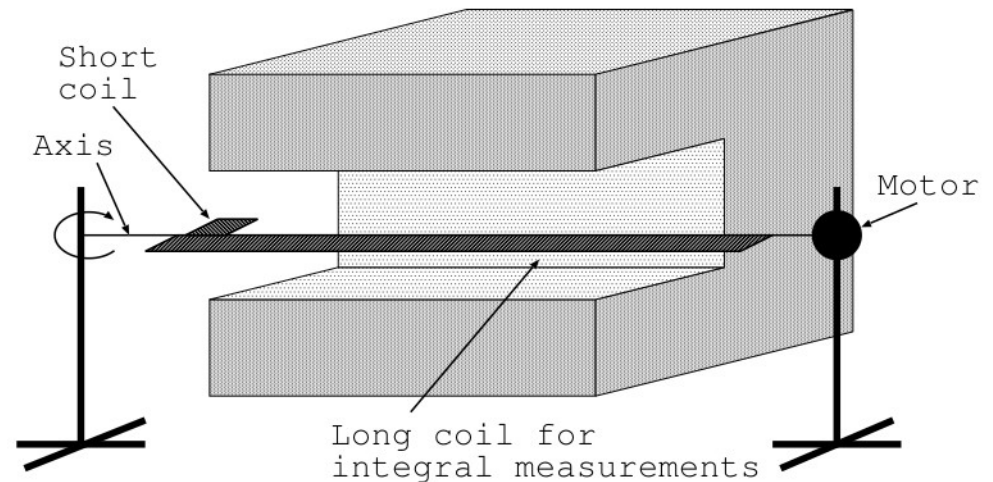
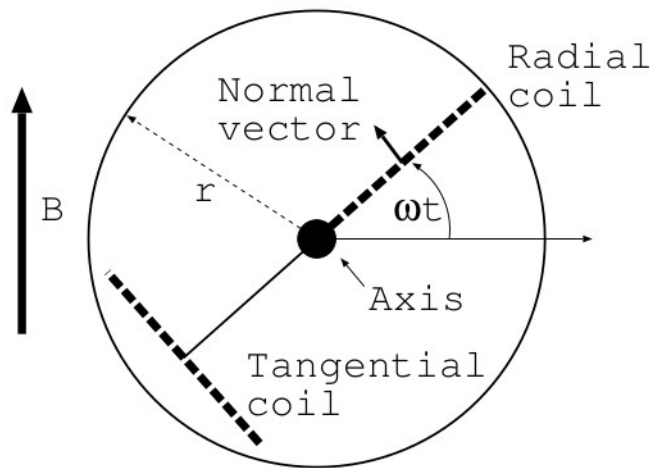
```

MATLAB



Magnet measurements with a rotating coil

- Rotating coil generates a voltage and the harmonics give the multipoles.





Alignment

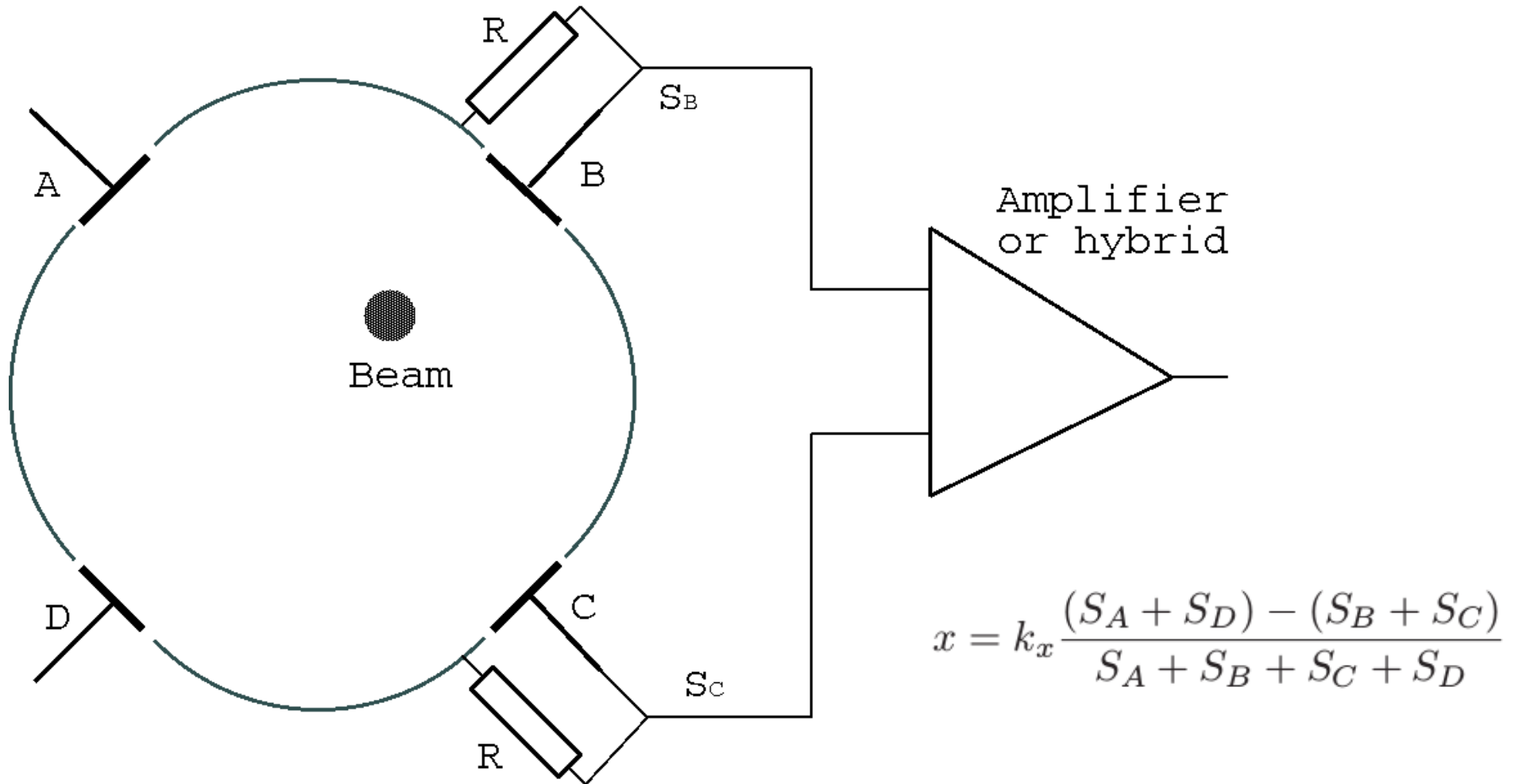
- How do you do it?
 - Magnets on tables
 - Fiducialization to pods
 - Triangulation
- How well can you do it?
 - 0.2-0.3 mm OK
 - <0.1 mm increasingly more difficult
 - more difficult in large installations
- Sub-micron for linear colliders → beam-based



Photo: R. Ruber, CTF3-TBTS



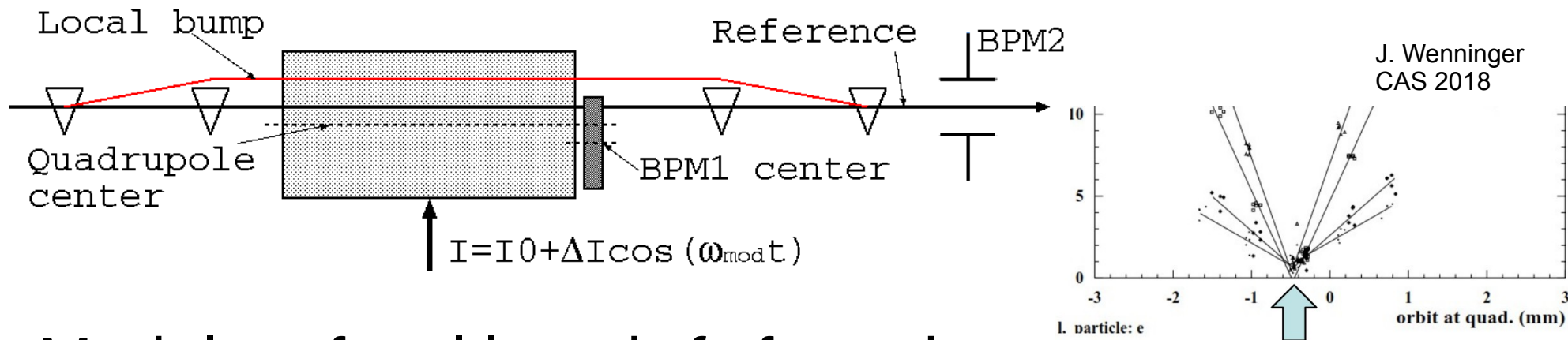
Beam Position Monitor





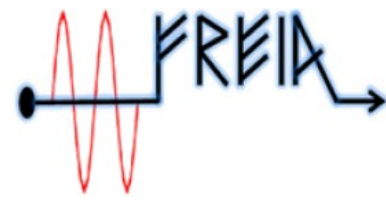
Find offsets with K-modulation

- BPM+Quadrupole are often mounted on the same support

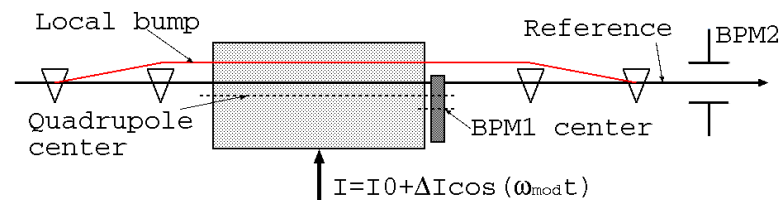
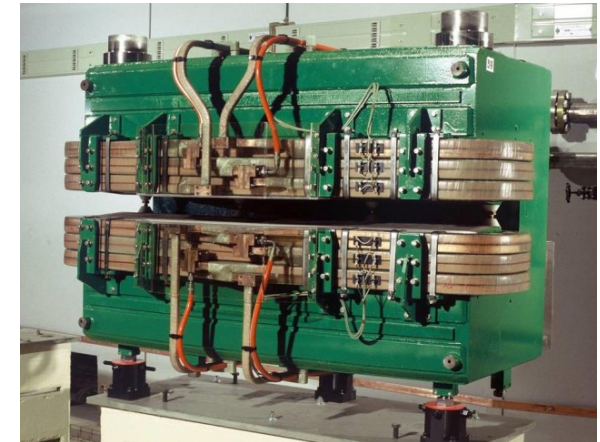


- Modulate focal length f of quadrupole
 - Kick from quadrupole $\Theta = x_{\text{offset}}/f(\omega)$ is also modulated
 - Observe on BPM2 and minimize signal by moving beam with a bump \rightarrow quadrupole center
 - Reading of BPM1 gives BPM1 offset rel. to quadrupole

Summary



- Accelerators
- Iron-dominated magnets
- Current-dominated magnets
- Permanent magnets
- Magnetic measurements
- Alignment





UPPSALA
UNIVERSITET

More fun courses...



...brought to you by **FREIA**

- 1FA330: Accelerator physics and Technology
- 1FA362: Permanent magnets
- 1FA348: Accelerators and Detectors (MJ++)
- 1FA361: Physics and Finance
- 1FA589: Optics and Photonics (VG)
- 1FA349: Sensor to Report

